

From General Systems Theory to Cyber-Physical System

The theory that is shaping our world ...

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Prepared for lecture EE5563 Microcontrollers and Embedded Systems

Lecture 8b

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Topic

1. Theory of Systems (L.Von Bertalanffy, 1972)
2. Real-Time Systems (Quest for Stability or Optimum State)

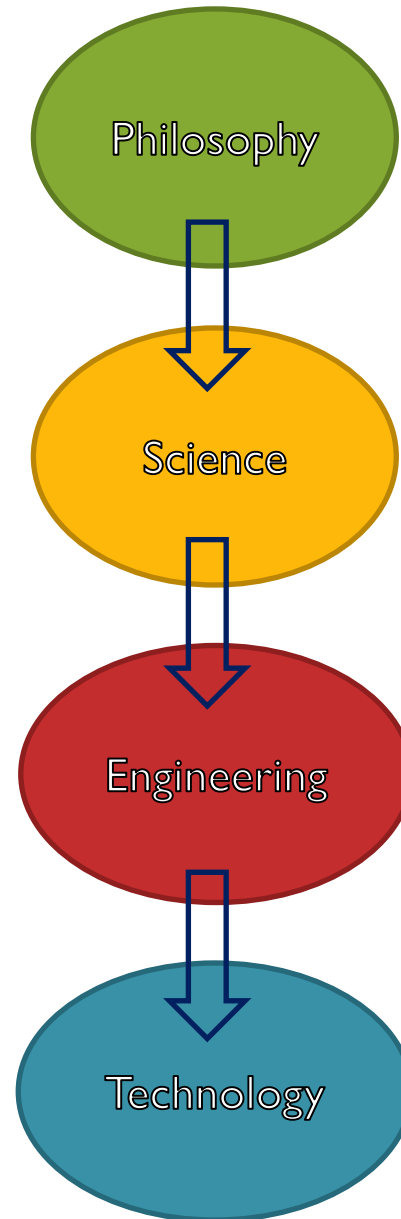


Fig 1

Prelude (L.Von Bertalanffy)

- Post Socrates Greek Philosophy
- There is an order or *Cosmos*: *intelligible* → *controllable by rational actions*
- Aristotle : “The **Whole** is more than **sum its parts**”
- Eastern Philosophers and Experimental, Scientists Aviceana, Khawrazmi, Toosi, Khayyam, ... linked philosophy to science – Mathematics
- Medieval thinker Cusa (15th cent): *coincidentia oppositorum* a fight amongst the parts within the whole
- In the west Galilean conceptions
- Newtonian Mechanical approach

Creation of Causal events described in mathematical language

Origins of Systems Modelling

- Second Maxim of Descartes “*Discourse de la Methode*”
- To understand the *Whole* we must know both parts of the relations
- We are now used to breaking down problems – isolating them
- However the challenge to the principles of isolating the components of complex problems is not new
- The “*How*” to integrate isolated systems is a major challenge for engineers!
- Simultaneous differential equations
- Continuous vs Discrete
- ...

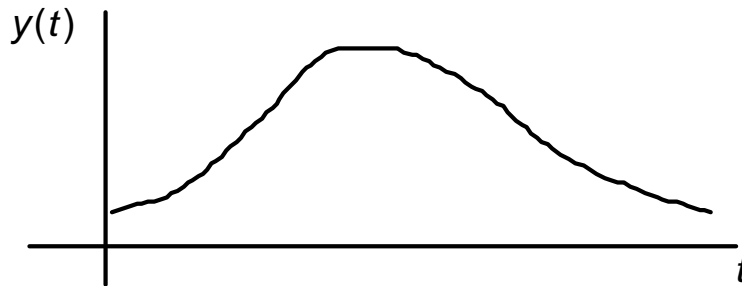
Purpose

- To understand (i.e. be able to explain)
- To relate excitation with behaviour
- To predict (what happens?)
- To stabilise (Control)
- To optimise (Operational Research)

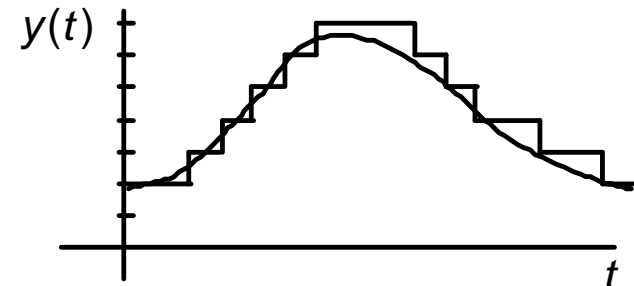
Why do you want to know about a system?

Observing Systems

- Continuous Analysis
- Discrete Analysis



(a) continuous time analog signal



(b) continuous time quantized signal

$$y^*(kT) = y(kT) \quad k = 0, 1, 2, 3, \dots$$

Types of Systems

- Mechanist → Total sum of members

Repetitive, Algorithmic, Stable Environment, Minimal Adaptability

- Organists → survival of the fittest (adaptation)

Darwinian, Adaptive, Responsive, Reactionary, Low Level of Intelligence, Optimisation, Customisation, Stochastic-Deterministic

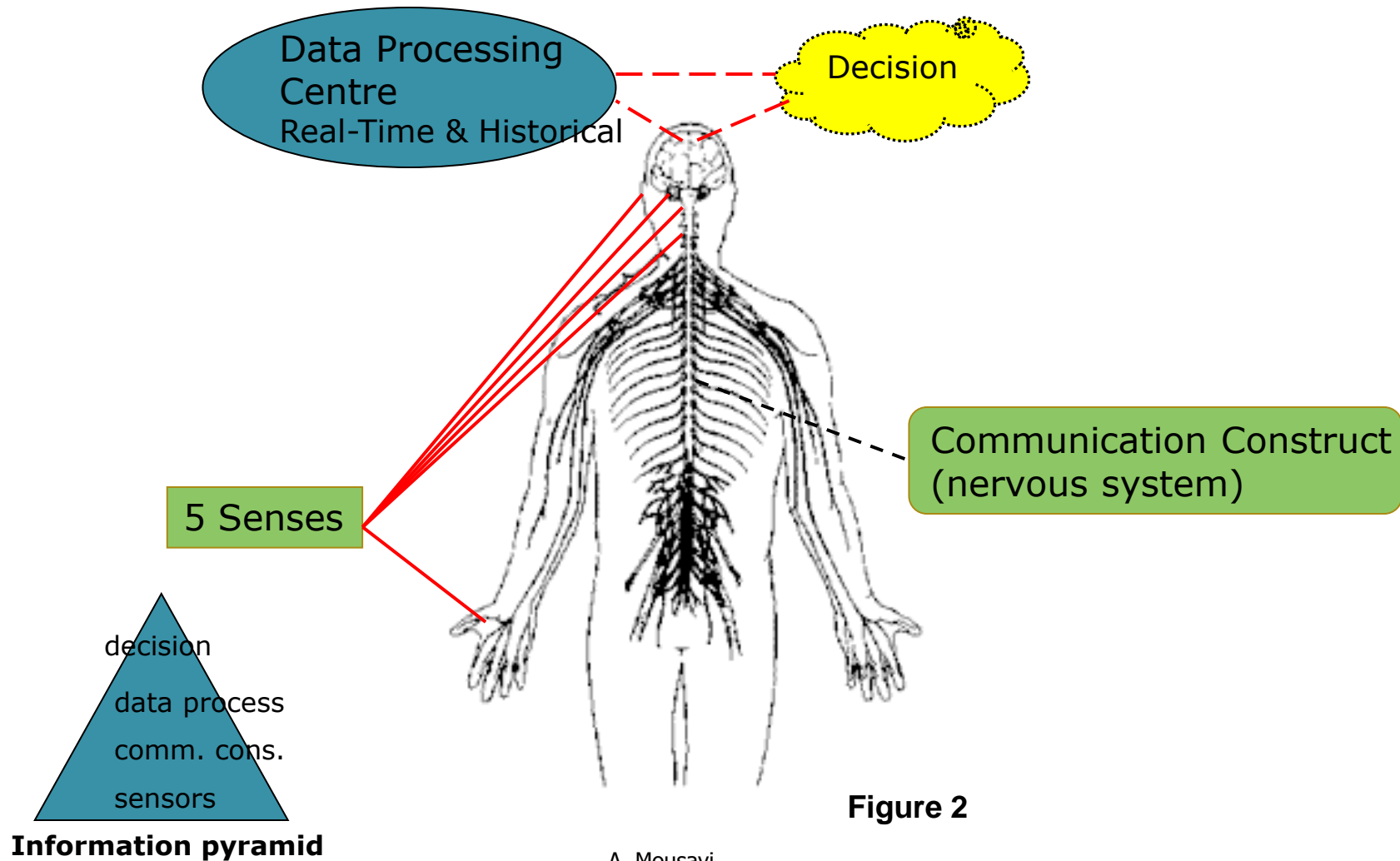
- **Viabile/Sustainable Systems**

All capabilities of organic system + High levels of intelligence, governs complex interactions, Active Learning, continuous monitoring & control, and aggressive prediction

- influence and change the environment to their advantage

- Reinvention – Creativity – Innovation

Adaptation + Sustainability



Data Modelling & System Performance Analysis (Descriptive)

- Data modelling is the process of preparing and translating **input data** into **meaningful information** in a specified **time span**
- There are various technique:
 - As simple as logical *AND, OR and IF* for binary systems
 - Complex data mining techniques such as; Statistical Process Analysis, Transfer Functions, Genetic Programming, Fuzzy Inference Analysis, Bayesian Belief Networks, ...

Attributes of Real-Time Data

- Created, Consumed, Collected by embedded systems
- Devices, Plants normally have SCADA systems
- Challenge is to make sense of it soon and take corrective action

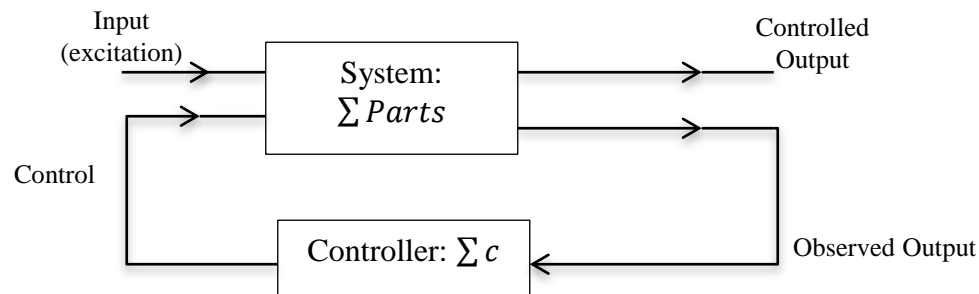


Fig 3

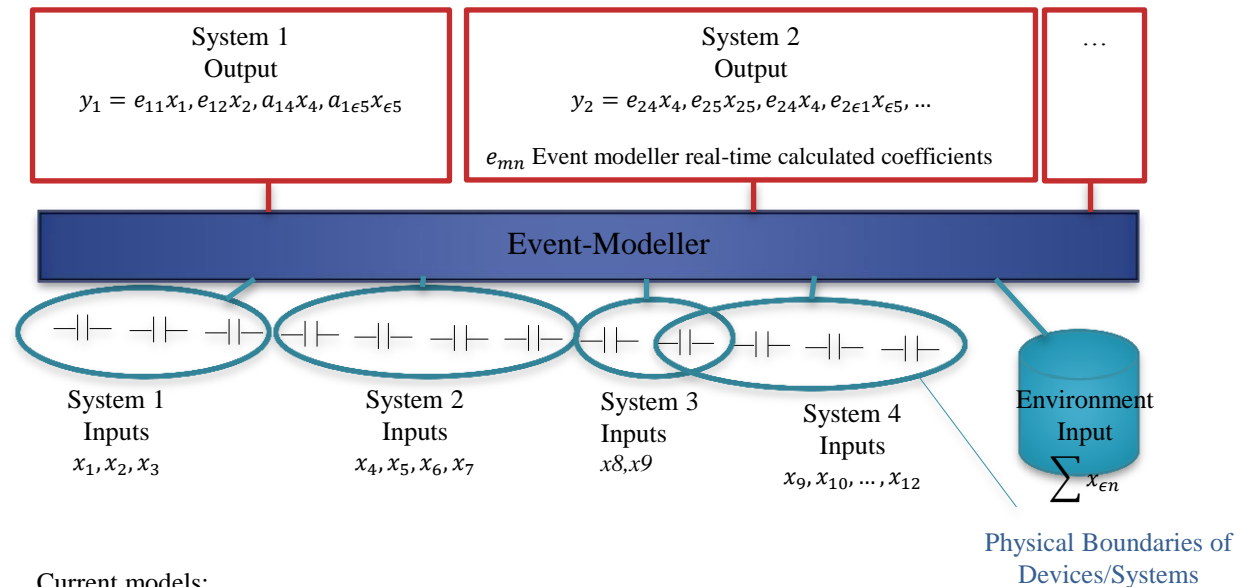
Event-Modelling (Mousavi et al 2013-14)

- The underpinning philosophy of the proposed technology is based on Decartes' philosophy of "*Discours de la Methode*",
- "*breakdown every problem into as many separate elements as possible*", and then **reassemble** it in the form of **eco-system of causality** of the smallest units.
- We also Borrow the concept of "*coincidentia oppositorum*" or the "*fight among parts*" from Cusa, and interpret the concept as the **causal interrelationships** of parts in the whole.
- In the language of engineering, how the excitation of the system driven by events and demonstrated by measurable inputs that contribute/affect the behaviour, stability and safety of a system.

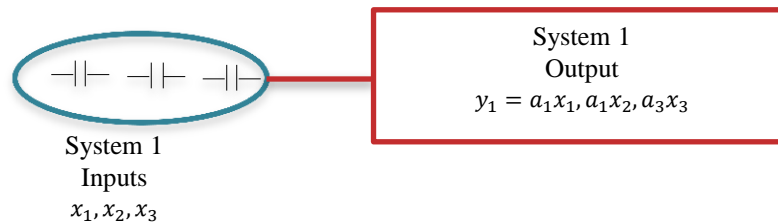
[\(back to Fig 3\)](#)

- Also Lorenzo's butterfly effect

Event-Modeller (tracker+cluster)

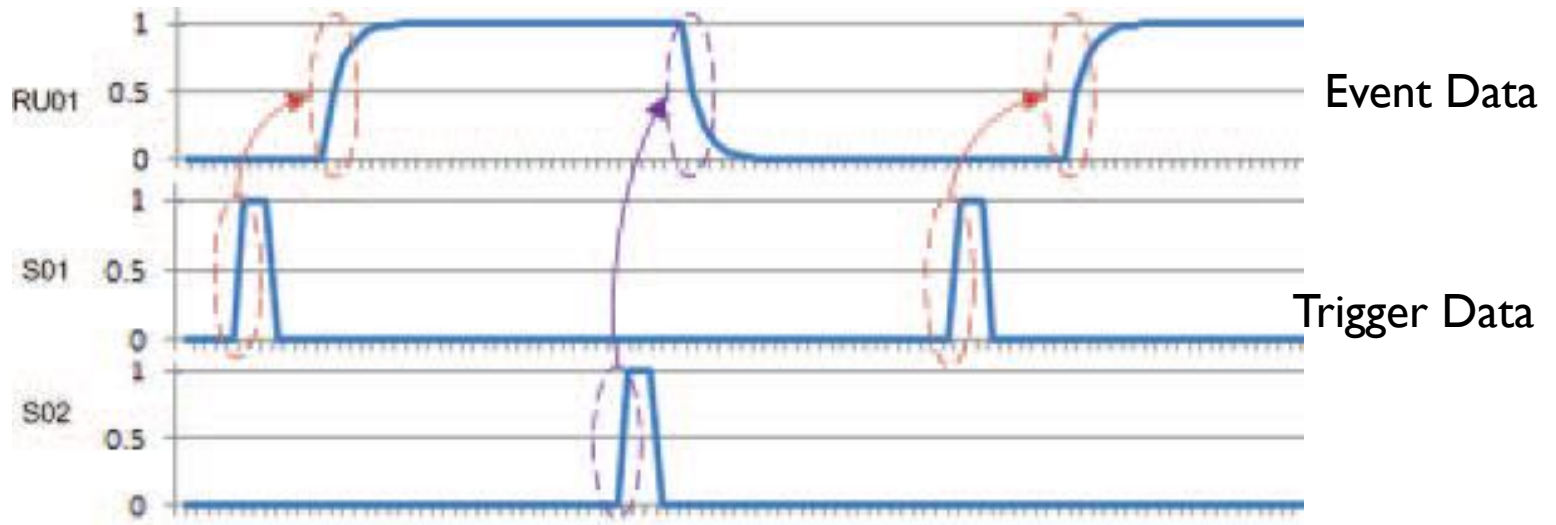


Current models:



a_n known or historically calculated coefficients

Event Tracker

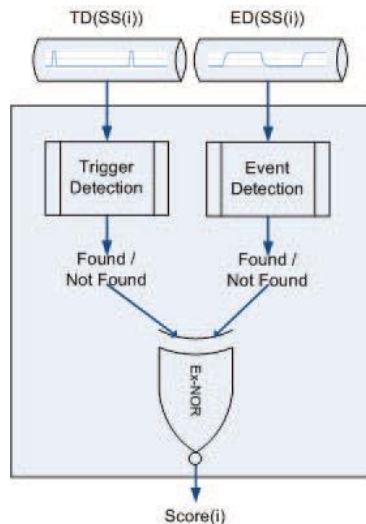


Event-Modeller Parameters

1. **Search slot (SS):** a fixed time in which batches of TD and ED are captured (system dependent)
2. **Analysis Span (AS):** the time period that a sensitivity analysis is conducted (AS contains a number of SS)
3. **Event Threshold (ET):** expressed as a percentage is the level of change in the value of an event determines whether a genuine event has occurred or not (e.g. change in flow rate)
4. **Trigger threshold (TT):** expressed as a percentage is the level of change in the value of a trigger determines whether a genuine event has occurred or not (e.g. sensor high/low)

The algorithm

1: Stepwise Scan & TT detection



2: Two-way Matching

| Input 1 | Input 2 | Output |
|---------|---------|--------|
| 0 | 0 | +1 |
| 0 | 1 | -1 |
| 1 | 0 | -1 |
| 1 | 1 | +1 |

3: Summation of two-way matching (Sensitivity Index at time t)

$$SI_{(t)} = \sum_{1}^{n} \text{Search Slot Scores}$$

Where n is number of Search Slot in an Analysis Span

Algorithm continued

4. Normalisation:

$$\tilde{S} = \frac{SI - l}{u - l}$$

Sensitivity index

Upper Bound

Lower Bound

The diagram shows the formula for the normalized sensitivity index, $\tilde{S} = \frac{SI - l}{u - l}$. Three blue lines point from text labels to the corresponding parts of the formula: 'Sensitivity index' points to the numerator 'SI - l', 'Upper Bound' points to the denominator 'u - l', and 'Lower Bound' points to the variable 'l' in the denominator.

An example for 10 search slot, 1 event and 3 sensors

2. Two-Way Matching Scores

1. Detected Events

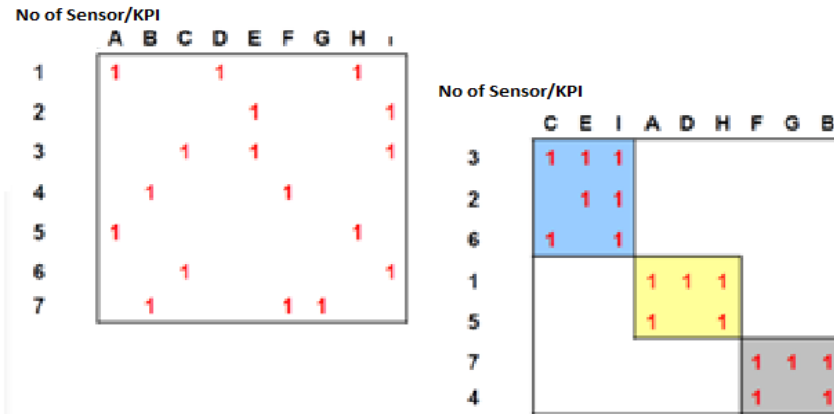
| Search Slot | 0 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 |
|-------------|------|------|------|------|------|------|------|------|------|------|------|
| ED | * | * | | * | | * | * | * | | * | * |
| TD1 | | | * | | | * | | | * | * | * |
| S1 | -1 | -1 | -1 | -1 | 1 | 1 | -1 | -1 | -1 | 1 | 1 |
| S11 | -1 | -2 | -3 | -4 | -3 | -2 | -3 | -4 | -5 | -4 | -3 |
| SIn1 | 0.00 | 0.00 | 0.00 | 0.00 | 0.00 | 0.00 | 0.00 | 0.00 | 0.00 | 0.00 | 0.00 |
| TD2 | * | | | | * | * | * | * | | * | |
| S2 | 1 | -1 | 1 | -1 | -1 | 1 | 1 | 1 | 1 | 1 | -1 |
| S12 | 1 | 0 | 1 | 0 | -1 | 0 | 1 | 2 | 3 | 4 | 3 |
| SIn2 | 1.00 | 1.00 | 1.00 | 0.67 | 0.33 | 0.33 | 0.67 | 0.75 | 0.80 | 0.80 | 0.75 |
| TD3 | | * | | * | | * | | * | | * | |
| S3 | -1 | 1 | 1 | 1 | 1 | 1 | -1 | 1 | 1 | 1 | -1 |
| S13 | -1 | 0 | 1 | 2 | 3 | 4 | 3 | 4 | 5 | 6 | 5 |
| SIn3 | 0.00 | 1.00 | 1.00 | 1.00 | 1.00 | 1.00 | 1.00 | 1.00 | 1.00 | 1.00 | 1.00 |

ED is most sensitive to TD3 and shows no sensitivity to TD1

3. Summation of two-way matches

4. Normalised sensitivity index

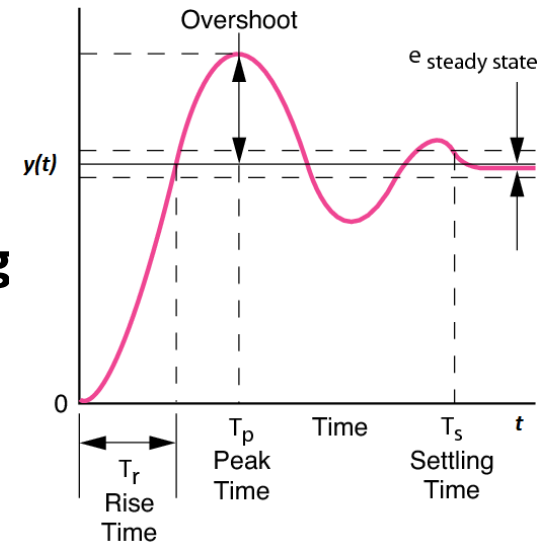
Event Cluster



- Group and linking a set of inputs to any given output
- Tests with 200 sensors and 2 Key performance indicators in Cement (energy & production output)
- 43000 real-time samples over 30 days
- Grouped all the relevant inputs to the 2 outputs.
- EventTracker and Event Cluster return the same results

Potentials and Future Work

- Use the technique to improve control transfer models and character equations
- Use the technique to deal with *Known-Unknowns* and potentially the *Unknown-Unknowns*!
- Technically and in real-time (**Engineering and Not Mathematically**) use the I/O relations to stabilise the system
- Optimise process by identifying the best process points and then adjusting the inputs to reach the desired output.
- Intelligent-Autonomous Control for Complex Systems



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