

Gradient, divergence and curl in cartesian coordinates

Gradient of ϕ .

$$\nabla\phi = \frac{\partial\phi}{\partial x}\underline{i} + \frac{\partial\phi}{\partial y}\underline{j} + \frac{\partial\phi}{\partial z}\underline{k},$$

Divergence of $\underline{E} = F_1\underline{i} + F_2\underline{j} + F_3\underline{k}$.

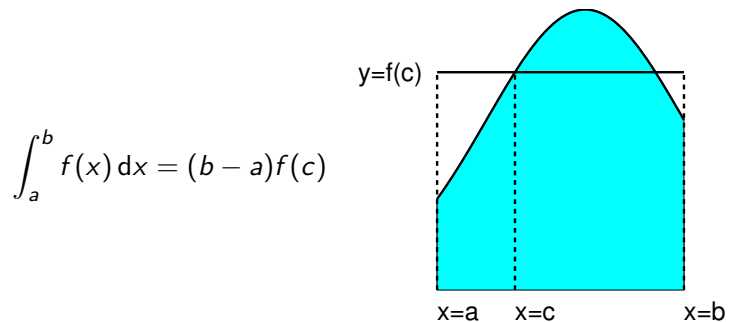
$$\nabla \cdot \underline{E} = \frac{\partial F_1}{\partial x} + \frac{\partial F_2}{\partial y} + \frac{\partial F_3}{\partial z},$$

Curl of $\underline{E} = F_1\underline{i} + F_2\underline{j} + F_3\underline{k}$.

$$\begin{aligned} \nabla \times \underline{E} &= \begin{vmatrix} \underline{i} & \underline{j} & \underline{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ F_1 & F_2 & F_3 \end{vmatrix} \\ &= \left(\frac{\partial F_3}{\partial y} - \frac{\partial F_2}{\partial z} \right) \underline{i} - \left(\frac{\partial F_3}{\partial x} - \frac{\partial F_1}{\partial z} \right) \underline{j} + \left(\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) \underline{k}. \end{aligned}$$

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The divergence and curl defined as a limit



Divergence as a limit: V is the volume inside surface S and point P is inside the surface which we shrink to \underline{P} .

$$\nabla \cdot \underline{E}(\underline{P}) = \lim_{V \rightarrow 0} \frac{1}{V} \int_S \underline{E} \cdot \underline{n} ds.$$

Curl as a limit: A is the area inside loop C and point P is inside the loop which we shrink to \underline{P} .

$$(\nabla \times \underline{E}(\underline{P})) \cdot \underline{n} = \lim_{A \rightarrow 0} \frac{1}{A} \oint_C \underline{E} \cdot d\underline{r}.$$

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Directional derivative, divergence and Stokes' theorems

Directional derivative of ϕ in the direction of \underline{n} .

$$\frac{\partial\phi}{\partial n}(\underline{r}) = \left. \frac{\partial}{\partial s} \phi(\underline{r} + s\underline{n}) \right|_{s=0} = \underline{n} \cdot \nabla\phi.$$

Divergence theorem.

$$\int_{\Omega} \nabla \cdot \underline{E} dv = \int_S \underline{E} \cdot \underline{n} ds,$$

$$\int_{\Omega} \nabla p dv = \int_S p \underline{n} ds.$$

Stokes' theorem.

$$\int_S (\nabla \times \underline{E}) \cdot \underline{n} ds = \oint_C \underline{E} \cdot d\underline{r}.$$

In the above \underline{n} denotes an appropriate unit vector in each case.

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Some vector identities involving \times and curl

For the cross product

$$\underline{a} \times \underline{b} = -\underline{b} \times \underline{a} \quad \text{which implies} \quad \underline{a} \times \underline{a} = \underline{0}.$$

$\underline{a} \times \underline{b}$ is orthogonal to both \underline{a} and \underline{b} .

For the base vectors

$$\underline{i} \times \underline{j} = \underline{k}, \quad \underline{j} \times \underline{k} = \underline{i}, \quad \underline{k} \times \underline{i} = \underline{j}.$$

$\nabla \times \underline{E}$ is divergence free as

$$\nabla \cdot (\nabla \times \underline{E}) = 0.$$

$\nabla\phi$ is irrotational in that

$$\nabla \times \nabla\phi = \underline{0}.$$

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