

## Anonymous or one line functions

Suppose that we have the following functions.

$$f_1(x) = \sin(x/6) - 1/2,$$

$$f_2(x) = \tan(x/4) - 1,$$

$$f_3(x) = \cos(x/3) - 1/2$$

In Matlab we can set these up and plot them with the following statements which uses anonymous functions.

---

```
f1 =@(x) sin(x/6)-0.5;
```

```
f2 =@(x) tan(x/4)-1;
```

```
f3 =@(x) cos(x/3)-0.5;
```

```
x=linspace(2*pi/3, 4*pi/3, 201);
```

```
figure(2)
```

```
plot(x, f1(x), '--', x, f2(x), x, f3(x), '-.')
```

## A function m-file for $\tan(x/4) - 1$

```
f2 =@(x) tan(x/4)-1;
```

A function file version of f2 is to have a file called f4.m which contains the following 2 lines.

---

```
function y = f4(x)
y = tan(x/4)-1;
```

---

## A function m-file solving $z^n = \zeta$

All the solutions to

$$z^n = \zeta = \rho(\cos(\alpha) + i \sin(\alpha))$$

are given by

$$z_k = \rho^{1/n} \left( \cos \left( \frac{\alpha}{n} + \frac{2k\pi}{n} \right) + i \sin \left( \frac{\alpha}{n} + \frac{2k\pi}{n} \right) \right), \quad k = 0, 1, \dots, n-1.$$

A function to implement this in the file `all_nth_roots.m` can be as follows.

---

```
function z = all_nth_roots(zeta, n)
r = abs(zeta);
t = angle(zeta);
s = t+2*pi*(0:(n-1));
s = s/n;
z = r^(1/n)*(cos(s)+1i*sin(s));
```

---

## A function m-file solving a quadratic equation

$$ax^2 + bx + c = 0, \quad x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}.$$

A function m-file in the file solve\_quadratic.m can be as follows.

```
function [x1, x2] = solve_quadratic(a, b, c)
d = b*b-4*a*c;
s = sqrt(d);
x1 = (-b-s)/(2*a);
x2 = (-b+s)/(2*a);
```

---

## Adding help comment lines

---

```
function [x1, x2] = solve_quadratic(a, b, c)
%% [x1, x2] = solve_quadratic(a, b, c)
% Given a~≠0, b and c the function generates the
% roots x1 and x2 of the quadratic a*x^2+b*x*c

d = b*b-4*a*c;
s = sqrt(d);
x1 = (-b-s)/(2*a);
x2 = (-b+s)/(2*a);
```

---

The comments are displayed when we type

```
help solve_quadratic
```

## The function header syntax

The first executable line in `myfun.m` has the following form.

```
function [y1, ..., yN] = myfun(x1, ..., xM)
```

1. Communication with other parts of a program are through the input and output arguments. All other quantities are local to the function.
2. We use the function with a statement of the form  
 $[b_1, \dots, b_N] = \text{myfun}(a_1, \dots, a_M)$
3. With only one function per file the statements are executed until a `return` statement is reached or until the end of the file is reached.

## Solving $f(x) = 0$ by the bisection method

Suppose  $f : [a, b] \rightarrow \mathbb{R}$  is continuous and  $f(a)f(b) < 0$ . This implies that there exists  $x \in (a, b)$  such that  $f(x) = 0$ .

We want a function which we can use as follows.

---

```
f1 =@(x) sin(x/6)-0.5;
```

```
f2 =@(x) tan(x/4)-1;
```

```
f3 =@(x) cos(x/3)-0.5;
```

```
[a1, b1] = bisec_meth(f1, 2, 4)
```

```
[a2, b2] = bisec_meth(f2, 2, 4)
```

```
[a4, b4] = bisec_meth(@f4, 2, 4)
```

```
[a3, b3] = bisec_meth(f3, 2, 4)
```

---

# A function implementing the bisection method

A candidate function file called `bisec_meth.m` is as follows.

---

```
function [a, b]=bisec_meth(f, a, b)

fa=f(a);
fb=f(b);

for k=1:200
    c=0.5*(a+b);
    fc=f(c);
    if fa*fc<=0
        b=c;
        fb=fc;
    else
        a=c;
        fa=fc;
    end
end
```

---

You should add statements to improve it.