

# MA1710: Key points in week 5 Matlab session

## Creating matrices with [ and ]

In mathematical notation consider the following.

$$A = \begin{pmatrix} 2 & -3 & 1 \\ 3 & 4 & -5 \\ 5 & -1 & -3 \end{pmatrix}, \quad \underline{b} = \begin{pmatrix} 0 \\ 2 \\ 1 \end{pmatrix}, \quad C = \begin{pmatrix} 2 & -3 & 1 & 0 \\ 3 & 4 & -5 & 2 \\ 5 & -1 & -3 & 1 \end{pmatrix},$$

In Matlab these can be created with the following statements.

```
A = [2 -3 1; 3 4 -5; 5 -1 -3]
```

```
b = [0; 2; 1]
```

```
C = [A, b]
```

## Referring to entries and blocks of entries

$$C = \begin{pmatrix} 2 & -3 & 1 & 0 \\ 3 & 4 & -5 & 2 \\ 5 & -1 & -3 & 1 \end{pmatrix},$$

In the Matlab version you can have the following.

```
v = C(3, 2)           % 3,2 entry
```

```
y = C(2, :)          % 2nd row
```

```
z = C(:, 3)           % 3rd column
```

## Creating a column of all the entries

$$C = \begin{pmatrix} 2 & -3 & 1 & 0 \\ 3 & 4 & -5 & 2 \\ 5 & -1 & -3 & 1 \end{pmatrix},$$

Consider the following statements.

$$y = C(2, :)$$

$$y = y(:)$$

The second statement creates a column vector of all the entries.

## Basic operations including the matrix product

We can multiply matrices by scalars, we can add them and the operator  $*$  means matrix multiplication. As examples you can do the following.

$$A = [2 \ -3 \ 1; \ 3 \ 4 \ -5; \ 5 \ -1 \ -3]$$

$$B = 5+2*A$$

$$x = [1; \ 1; \ 1]$$

$$z = A*x$$

## The matrix product continued

In the following we create  $A$  and  $B$  and we create the matrix products  $AB$  and  $BA$ .

$$A = [2 \ -3 \ 1; \ 3 \ 4 \ -5; \ 5 \ -1 \ -3]$$

$$B = 5+2*A$$

$$AB = A*B$$

$$BA = B*A$$

## Solving linear equations using \

When  $A$  is a  $n \times n$  matrix and  $\underline{b}$  is a  $n \times 1$  matrix we often wish to attempt to solve the linear equations

$$A\underline{x} = \underline{b}.$$

In Matlab this can be done with the following statement.

$$\underline{x} = A \setminus \underline{b}$$

# The functions zeros, ones and eye

The following Matlab statements

```
Z = zeros(3, 5)
```

```
O = ones(3)
```

```
I3 = eye(3)
```

create the following output.

```
Z =
```

```
    0    0    0    0    0
    0    0    0    0    0
    0    0    0    0    0
```

```
O =
```

```
    1    1    1
    1    1    1
    1    1    1
```

```
I3 =
```

```
    1    0    0
    0    1    0
    0    0    1
```

## The functions `inv` and `rref`

In your linear algebra lectures you learn about the matrix inverse and the reduced row echelon form. Matlab has functions for these which can be used as follows.

```
C = [2 -3 1 -1; 3 4 -5 -4; 5 -1 -3 -6];
```

```
A3 = C(:, 1:3)
```

```
A3I = inv(A3)
```

```
rC = rref(C)
```

```
A3 =
```

```
    2    -3     1
    3     4    -5
    5    -1    -3
```

```
A3I =
```

```
    1.8889    1.1111   -1.2222
    1.7778    1.2222   -1.4444
    2.5556    1.4444   -1.8889
```

```
rC =
```

```
    1     0     0     1
    0     1     0     2
    0     0     1     3
```